

# INFONET Seminar Application Group Frequency Domain Compressive Sensing for Ultrasound Imaging

Celine Quinsac, Adrian Basarab  
Advances in Acoustic and Vibration April 2012

*Presenter Pavel Ni*



Gwangju Institute of  
Science and Technology

# Introduction

Conventional Ultrasound imaging systems rely on Shannon-Nyquist theorem. Often US devices use a sampling rate that is at least four times the central frequency.

Consequently large amount of data imply problems in:

- Real-time imaging (especially 3D)
- Data-transfer
- Grows of machinery size

Compressive sensing allows reduce volume of data directly acquiring compressed signal. Recently CS framework was adopted to ultrasound imaging [10-15] (all paper except one are conference papers), Ultrasound Doppler [16-17] or Photoacoustic [18]

# Sampling a signal

Sampling can be summarized by measuring linear combination of an analog signal

$$y_k = \langle \varphi_k, f \rangle, \quad \text{for } k = 1, \dots, m, \quad (1)$$

Where  $y_k$  are the measurements,  $\varphi_k$  are sampling vectors, and  $m$  is the number of measurements. The most common sampling protocol consist of vectors of Dirac's at equal time. The measurements then simple discretization of  $f(t)$ .

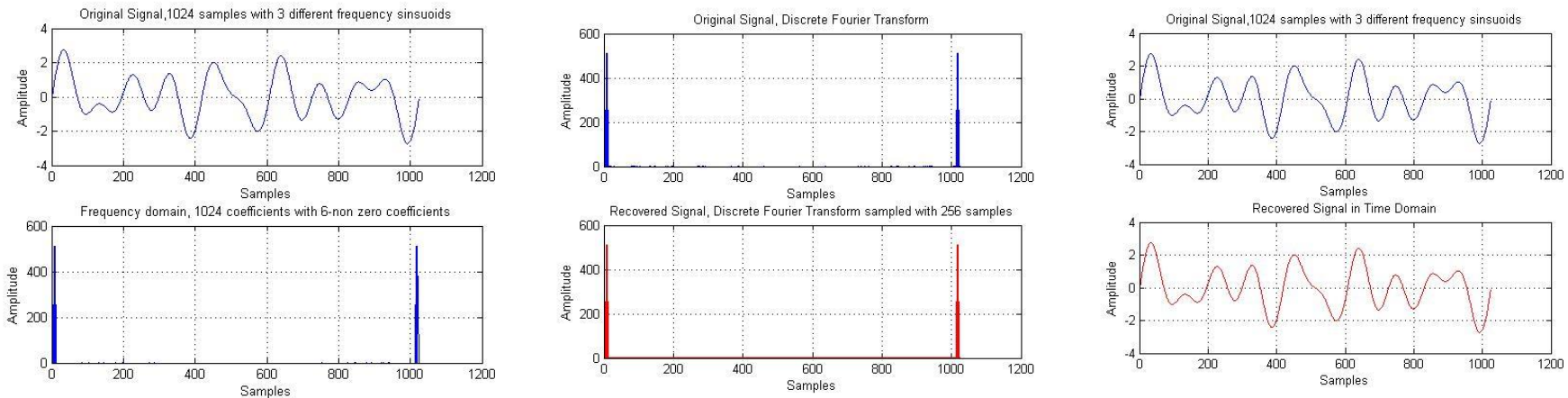
In CS, the number of measurements is  $m \ll n$ . However, when the number of measurements is smaller then the signal size, then it is ill-posed inverse problem.

If  $\Phi$  is a matrix of size  $m \times n$ , concatenating the sampling vectors  $\varphi_k$ , then  $y = \Phi f$ . The signal  $\hat{f}$  corresponding to the measurements  $y$  has infinity many solutions.

CS shows that  $\hat{f}$  can be reconstructed if it has sparse representation in a given basis and that the measurements are incoherent with that basis.

# Concept of Sparsity

Sparsity is the idea that signal may have a concise representation in a given basis.



Hence a dense signal in the time domain can be coded with only a few samples. Mathematically it translates as follows:

$$f(t) = \sum_{i=1}^n x_i \psi_i(t) \quad (2)$$

Where  $f(t)$  is the original signal,  $x_i$  are the coefficients of the signal in sparse basis, and  $\psi_i(t)$  is an orthonormal basis. The  $S$  largest coefficients  $x_i$  are noted  $x_S$ , and the corresponding signal  $f_S(t)$ . If  $f(t)$  is sparse in the basis  $\Psi$  composed of the vectors  $\psi_i$ , then  $f = \Psi x$  and the error  $\|f - f_S\|_2$  is small.

# Concept of Sparsity

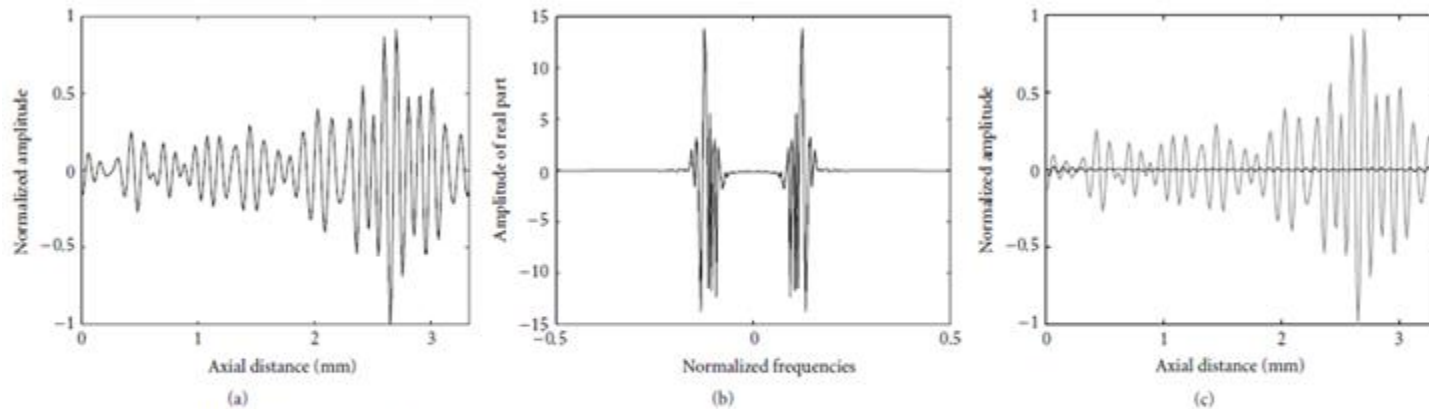


FIGURE 1: (a) A full US RF signal and (b) its sparse representation via Fourier transform. Most of the coefficients are equal or close to zero. (c) Compressed US RF signal (gray), corresponding to 30% of the largest Fourier coefficients, the rest of them being set to zero. The difference between the full and compressed US RF signal (black) is minimal.

- Sparsity therefore leads to compressive nature of signal: if signal has sparse representation, then the information coding that signal can be compressed on a few coefficients.
- However directly acquire only significant coefficients without knowing their positions is impossible.
- CS overcomes this issue via an incoherent sampling.

# Incoherent Sampling

The term Incoherent sampling conveys the idea that the sampling protocol  $\phi_k$  in (1) has to be as little correlated as possible with sparse representation  $\psi_i$  in (2).

$$y_k = \langle \phi_k, f \rangle, \quad \text{for } k = 1, \dots, m, \quad (1) \quad f(t) = \sum_{i=1}^n x_i \psi_i(t) \quad (2)$$

The mathematical definition of incoherence is:

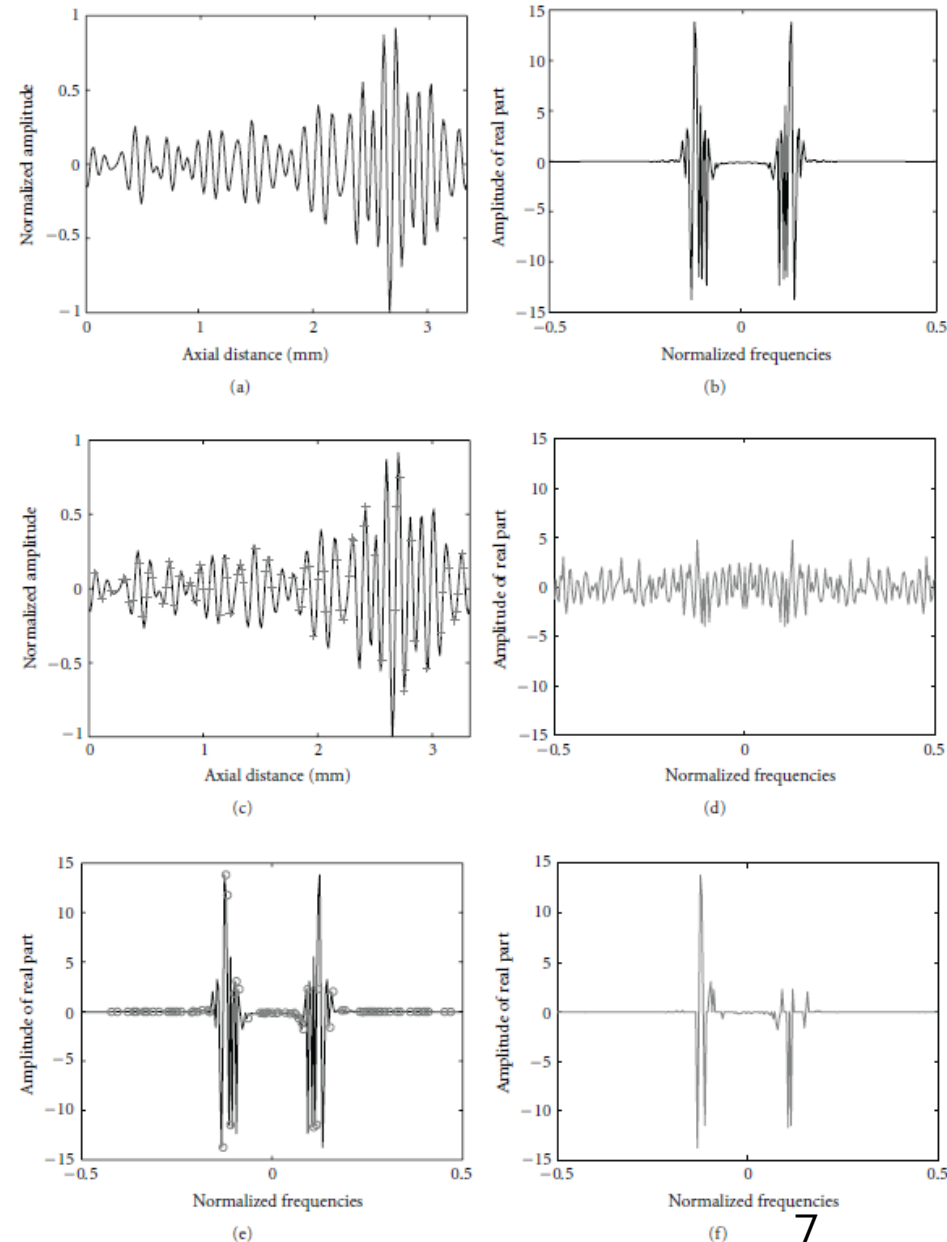
$$\mu(\Phi, \Psi) = \sqrt{n} \max_{1 \leq k, j \leq n} |\langle \phi_k, \psi_j \rangle|, \quad (3)$$

Where  $\Phi$  is the sampling basis and  $\Psi$  is the sparsifying basis. If the two bases are strongly correlated, then  $\mu$  will be close to  $\sqrt{n}$ , and if they are not correlated, then it will be close to 1.

- CS requires incoherence .
- If the sampling basis is completely random , then it will be maximally incoherent with sparsifying fixed basis.

# Incoherent Sampling

- (a) A full US RF signal
- (b) its sparse representation FT
- When sampling is incoherent with the sparsifying basis then the measurements in that basis are dense (c, d)
- When the sampling basis and the sparsifying basis are coherent (e,f), the measurements in the sparsifying basis are themselves sparse. There is significant information missing
- Knowing sparsifying basis and incoherent measurements in cs make it possible to reconstruct original signal using optimization.



# Signal Reconstruction through Optimization

Reconstruction performed via convex optimization:

$$\min \|\hat{x}\|_1 \quad \text{subject to } y = \Phi f = \Phi \Psi \hat{x}, \quad (4)$$

$\hat{x}$  is the reconstructed sparse signal.

The optimization searches amongst all the signals that verify the measurements  $y$ , the one with the smallest  $l_1$  norm, that is the sparsest.

Optimization removes the interferences caused incoherent under sampling from the sparse representation of the measurements.



# Sampling Protocols in Ultrasound

The data acquisition in US is performed in spatial domain. The sampling basis has to be incoherent with sparsifying basis. There are several sampling protocols adapted and incoherent with sparsifying basis. Basically they all consist in taking samples at random locations (taking samples at specific times on RF signal or taking some RF lines at specific locations)

- Eight different protocols are proposed:

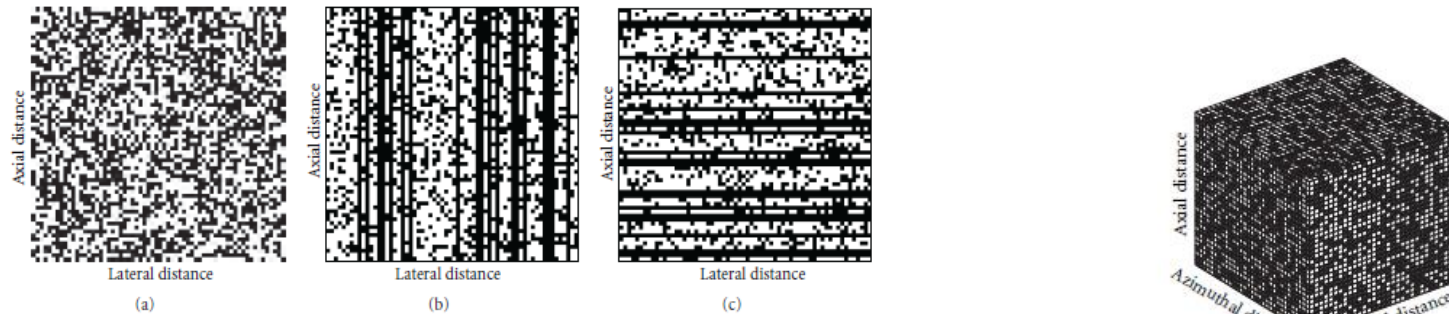


FIGURE 6: Sampling masks  $\Phi_1$  (a),  $\Phi_2$  (b), and  $\Phi_3$  (c) adapted to a spatial sampling of the US images. The white pixels correspond to the samples used for CS. The proportion of samples here is 50% of the original image.

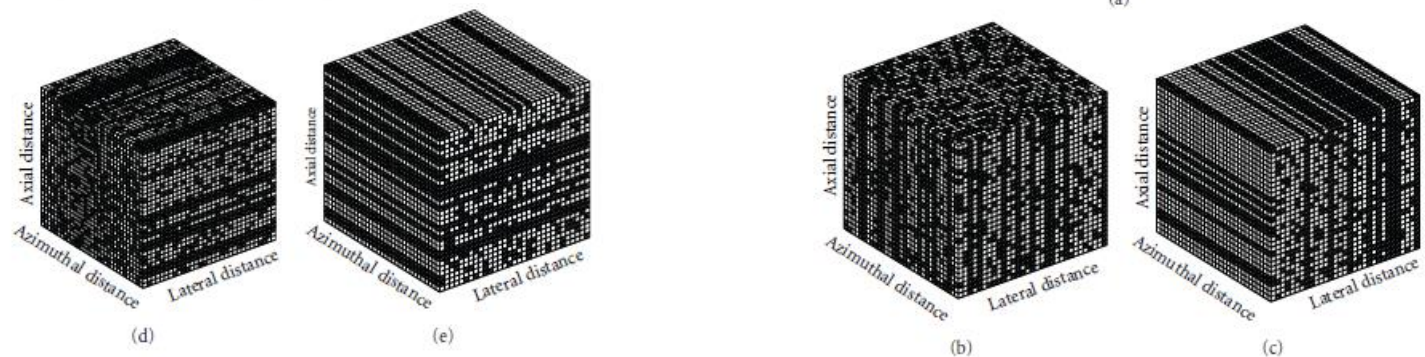


FIGURE 7: Sampling masks  $\Theta_1$  (a),  $\Theta_2$  (b),  $\Theta_3$  (c),  $\Theta_4$  (d), and  $\Theta_5$  (e) adapted to a spatial sampling of the 3D US volumes. The white pixels correspond to the samples used for CS. The proportion of samples here is 50% of the original volume.

## Reconstruction of Ultrasound Images

The acquisition consist in taking samples of the RF signals. This sampling protocol is similar to a basis of Diracs. Basis incoherent with Diracs and where US images are sparse is needed. Fourier basis is maximally incoherent with Diracs and because the US image k-space is sufficiently sparse. The function to minimize is

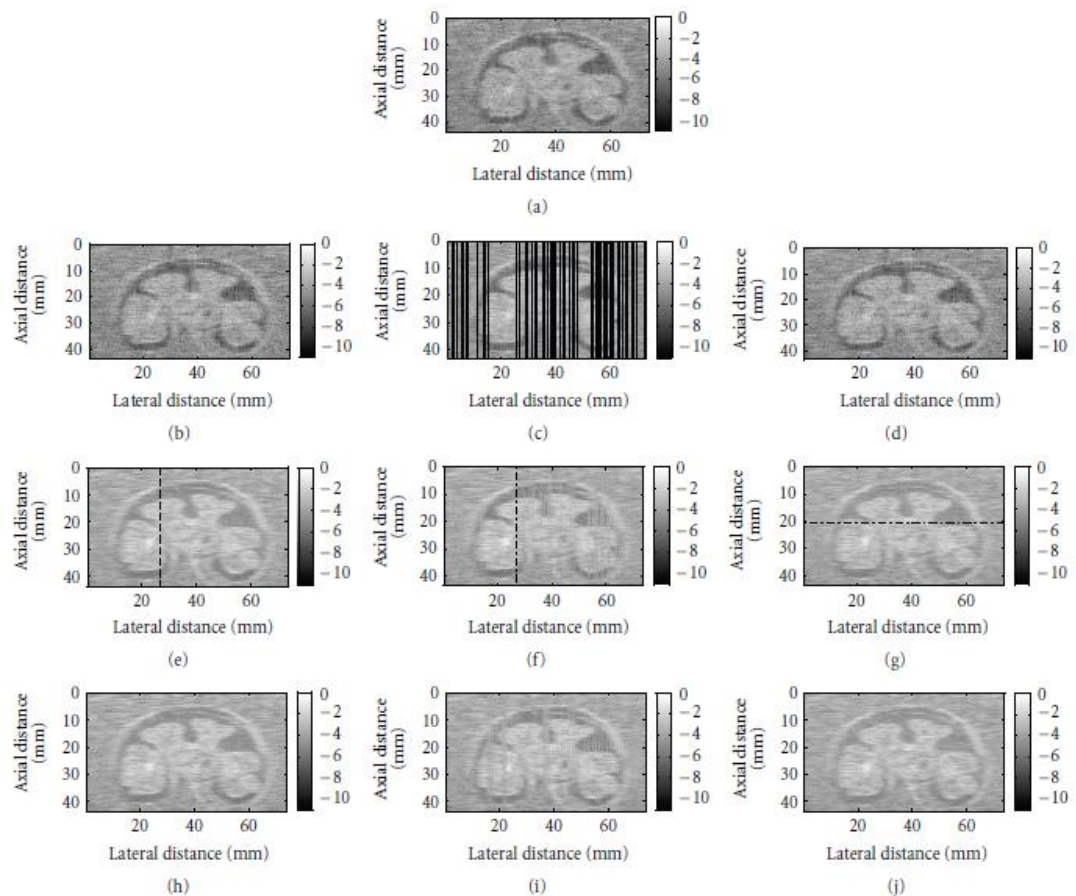
$$\arg \min_M \|AM - y\|_2 + \lambda \|M\|_1, \quad (8)$$

where  $M$  is the k-space of the US RF image  $m$  ( $M = Fm$ ), and  $A$  is the sampling scheme ( $A = \Phi F$ ),  $y$  are the RF US image measurements and  $\lambda$  is a coefficient weighting for sparsity.

## Results on a 2D Simulation Image

The proposed CS method was used to reconstruct the k-space of an RF image simulated using the Field ii simulation program. Map of kidney used with linear transducer. Sampling frequency 20 MHz.

The sampling  $\Phi_1, \Phi_2, \Phi_3$  were studied to compare CS reconstruction using a fixed optimal set to 0.005 and the reweighted  $\lambda$  minimization  $\ell_1$



# Results on a 2D Simulation Image

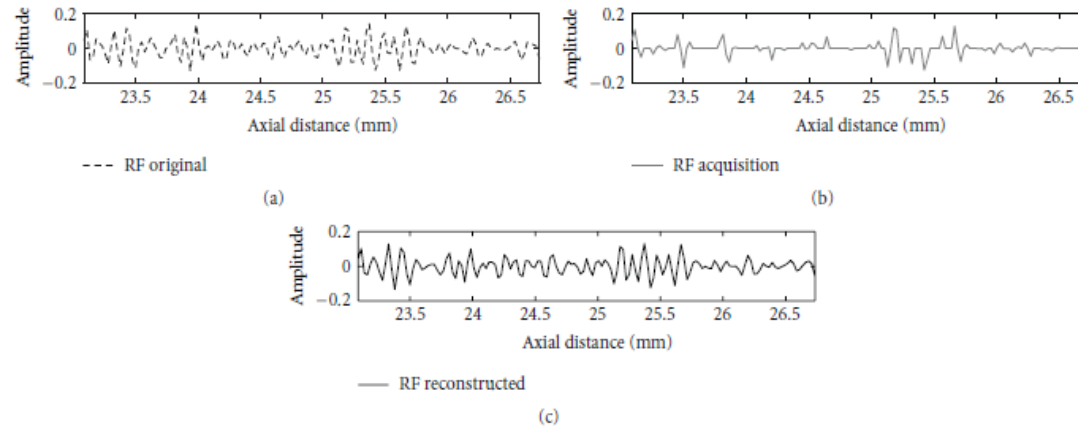


FIGURE 9: An example of a local region of an RF line after CS reconstruction using  $\Phi_1$  sampling pattern, corresponding to the dotted line in Figure 8(e).

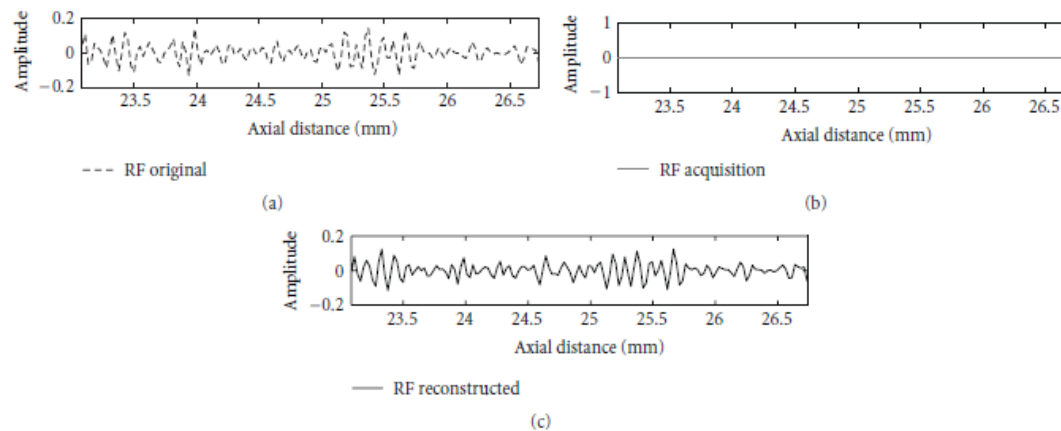


FIGURE 10: An example of a local region of an RF line after CS reconstruction using  $\Phi_2$  sampling mask, corresponding to the dotted line in Figure 8(f). This line was not sampled at all.

# Results on a 2D Simulation Image

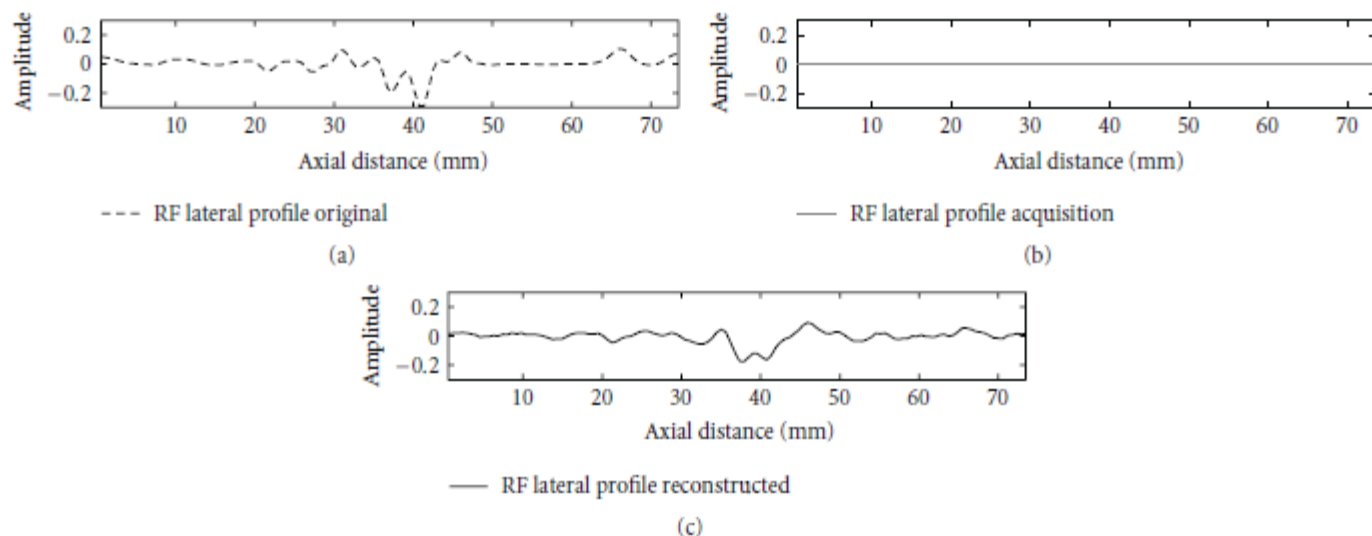


FIGURE 11: An example of a lateral profile of aN RF image after CS reconstruction using  $\Phi_3$  sampling mask, corresponding to the dotted line in Figure 8(g). This lateral profile was not sampled at all.

TABLE 1: NRMSE between the CS-reconstructed RF US image and the original simulated image of a kidney for different sampling ratios and patterns.

		$\Phi_1$	$\Phi_2$	$\Phi_3$
Classic $\ell_1$ minimization ( $\lambda = 0.005$ )	25%	0.48	0.58	0.6
	33%	0.33	0.45	0.49
	50%	0.15	0.28	0.29
Reweighted $\ell_1$ minimization	25%	0.51	0.56	0.64
	33%	0.36	0.47	0.49
	50%	0.17	0.24	0.3

## Discussion and Conclusion

Sampling using high sampling rate is neither easy nor cost-effective in high frequency applications.

It was showed potential of CS to reduce data volume and wrap acquisition at the price of a reconstruction using the  $\ell_1$  norm.

Future work

- Better sparsity basis
- Investigation of several optimization routines
- The aim is to reach fastest and most reliable reconstruction from as little amount of data as possible.

**Thank you**